

## Description

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*insB1* 5 Circuit arrangement for two-wire/four-wire conversion in a DMT system with nonlinear echo cancellation

The present invention relates to a circuit arrangement for two-wire/four-wire conversion in a DMT system in accordance with the preamble of claim 1, as disclosed in EP-A-0 488 369.

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*B* BACKGROUND

US-A-3,647,992 discloses a circuit arrangement for two-wire/four-wire conversion in a DMT system, which is connected to a digital reception path, a digital transmission path and also an analog transmission/reception path and which has nonlinear echo cancellation in the time domain and also has a device for adaptation of the nonlinear echo cancellation in the frequency domain.

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US-A-5,778,055 discloses nonlinear echo cancellation in connection with an analog telephone system.

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US 5,317,596 describes a method and a device for echo  
cancellation in the case of a signal generated by  
discrete multitone modulation. As is known, full-duplex  
data transmission is the simultaneous transmission of  
5 data in two opposite directions with partly overlapping  
frequency bands. In this case, an echo occurs as a  
result of a signal to be transmitted crossing into the  
receiver situated at the same location, as a result of  
which a signal received by the remote end is superposed  
10 and corrupted. By way of example, an echo occurs in a  
telephone network if the signal transmitted by a user  
passes through the hybrid circuit into the receiver of  
the user. This hybrid circuit may also be referred to  
as an echo channel. Such an echo channel can be modeled  
15 by a finite number of parameters. Therefore, an echo  
canceler first estimates the parameters and then  
linearly convolves the estimation with the transmitted  
signal, as a result of which the echo is emulated. The  
emulated echo signal thus obtained is then subtracted  
20 from the received signal, whereby the pure signal is  
produced in the ideal case.

Echo principally occurs owing to inexactly matched  
impedances at the hybrid connectors. Since the  
25 impedances of the transmission lines are time-dependent  
and line-dependent, the echo canceler must be adaptive.  
Furthermore, it is possible to carry out echo  
cancellation both in the time domain and in the  
frequency domain of a signal.

In multicarrier modulation, the data to be transmitted are transmitted by the binary digital data that are to be transmitted first being arranged in sub-blocks. These sub-blocks are then combined to form blocks of fixed length which are then in each case modulated onto a carrier and transmitted. Discrete multitone modulation is a form of multicarrier modulation which is used in digital signal processing, an IFFT/FFT pair being used as modulation/demodulation vector.

In the US patent specification mentioned, the echo cancellation is performed both in the time domain and in the frequency domain of a signal. What is disadvantageous is that only linear echo cancellation is performed, so that complete echo cancellation is not achieved.

Furthermore, methods are known in which the cancellation of the nonlinear echo signal is effected in the time domain and the attenuation of the linear echo signal is preferably effected in the frequency domain. This gives rise to difficulties in the adaptation due to slow transient recovery and convergence problems.

Furthermore, WO 98/32241 describes a circuit arrangement for two-wire/four-wire conversion, in which digital signals of a digital reception path are converted and coupled via a hybrid onto an analog transmission/reception path and analog signals of the analog transmission/reception path are digitized and coupled onto a digital transmission path, echo suppression being connected between the digital transmission and reception paths. In this case, an echo estimation filter is used to adaptively approximate the behavior of the hybrid circuit and of the analog transmission/reception path. In this case, the echo cancellation is effected both in the frequency domain

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and in the time domain of the signals, which causes difficulties in the adaptation.

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**SUMMARY**

The invention is based on the object, therefore, of  
5 developing effective echo cancellation in systems with multicarrier modulation with orthogonal subchannels.

The object is achieved by means of the features of the device according to claim 1 and of the method according  
10 to claim 9. The ~~sub~~claims relate to the preferred refinements of the invention.

In the invention's method and device for attenuating nonlinear echo signals in a circuit arrangement for  
15 two-wire/four-wire conversion with multicarrier modulation with orthogonal subchannels, for example "Discrete Multitone Modulation" (DMT), "Orthogonal Frequency Division Multiplex" (OFDM) or "Discrete Wavelet Multitone" (DWTM), the modeling of the  
20 nonlinearities is effected in the frequency domain of a signal, while the nonlinear echo cancellation is effected in the time domain of the signal.

A pilot tone is used for adaptation of the nonlinear  
25 modeling. The nonlinearities of the transmission system, in particular of the line driver, cause harmonics, i.e. frequencies at even-numbered multiples of the fundamental frequency occur. Furthermore, said fundamental frequency is altered in magnitude and phase  
30 via the linear echo path.

In the frequency domain of the signal, the modeling of nonlinearities is composed of a linear part and a nonlinear part, the linear part, since only the pilot  
35 tone is used, being reduced to complex number  $a_1$  (magnitude and phase), or, since two linear models are necessary, to two complex numbers  $a_1$  and  $a_2$ . The

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nonlinear model is described by the dependence of fundamental relative to the respective harmonics.

5 The adaptation is effected by means of an error signal composed of the difference between the received signal and the estimated echo. In this case, firstly the linear model and then the nonlinear model are adapted. The nonlinear model can be approximated by a Taylor series. In this case, the Taylor series is preferably  
10 terminated after the quadratic element.

The coefficients of the nonlinear model are then transferred to the nonlinear time model.

15 Figure 1 shows a circuit diagram of echo cancellation according to the invention.

### *DETAILED DESCRIPTION*

20 Via a digital reception path 1, the signal passes via an IFFT 4 (Inverse Fast Fourier Transformation), a D/A converter 5, a filter 6, a line driver 7 into the hybrid or echo path 8 and onto an analog transmission/reception path 3. A received analog signal passes via a filter 9, an A/D converter 10, an FFT 11 (Fast Fourier Transformation) onto the digital  
25 transmission path 2.

30 In the echo path or hybrid 8, an echo of the digital transmission signal passes into the reception path of the digital transmission signal, is added to the analog reception signal and therefore leads to interference.

35 For cancellation of the echo signal, a nonlinear echo canceler 12 comprising a first filter 13, a nonlinear unit 14 and a second filter 15 is provided in the time domain, i.e. downstream of the IFFT 4 and upstream of the FFT 11, of the circuit arrangement. Furthermore, the nonlinear echo canceler 12 has an adder 16, in which the signal downstream of the first filter 13 is

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subtracted from the signal downstream of the nonlinear unit 14. The cancellation signal, i.e. the estimated echo, is subtracted from the analog signal comprising the reception signal and the echo in a further adder 17.

Furthermore, the circuit has a linear echo canceler 18 in the frequency domain, i.e. upstream of the IFFT 4 and downstream of the FFT 11, whose estimated echo signal is subtracted, in an adder 19, from the digitized signal comprising the reception signal without the nonlinear echo component.

For adaptation of the nonlinear echo canceler 12, the circuit has a device 20 for adaptation of the nonlinearities, which comprises a first linear model 21, a nonlinear model 22 and a second linear model 23, the pilot tone being fed to the device 20. The first and second linear models 21, 23 are adapted by means of an error signal which, in an adder 24, is composed of the estimated echo and the reception signal with the linear echo component. The nonlinear model is adapted by means of an error signal which, in a further adder 25, is composed of the estimated echo and the reception signal. The coefficients of the nonlinear model 14 are transferred to the nonlinear unit 14 of the nonlinear echo canceler 12.

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